

What Is Claimed Is:

1. A method for triggering a restraint system, an acceleration signal which is characteristic for a collision being generated; the acceleration signal being on the one hand integrated to form a speed signal and on the other hand being used to determine a threshold value for the speed signal; the threshold value being adapted by a variable ($\Delta V_{\text{ADD-ON}}$) which is determined from a plurality of characteristics of the acceleration signal and/or of the speed signal and/or of at least one further sensor signal; and the restraint system being triggered as a function of a comparison of the speed signal (ΔV_x) with the adapted threshold value ($\Delta V_{\text{XTH-ADD}}$).
2. The method as recited in Claim 1, wherein the plurality of characteristics are determined as a function of a hammer blow and/or an integration window and/or a signal from an up-front sensor and/or as a function of a signal variation caused by a deformable barrier and/or by a pattern detection.
3. The method as recited in Claim 1 or 2, wherein the plurality of characteristics are combined by an adder (8).
4. The method as recited in one of Claims 1 through 3, wherein at least one amplifier (7) is used to assess the variable.
5. The method as recited in Claim 4, wherein the amplifier (7) is adjusted adaptively.
6. The method as recited in one of the foregoing claims, wherein a filter (3) is used for filtering the acceleration signal before the threshold value

calculation (4).

7. The method as recited in one of the foregoing claims, wherein at least some of the characteristics and/or the at least one sensor signal are logically linked to one another in order to determine the variable ($\Delta V_{\text{ADD-ON}}$).
8. The method as recited in Claim 7, wherein the linking is performed by a matrix.
9. The method as recited in Claim 8, wherein both dynamic and static characteristics are linked in the matrix.
10. Use of a control unit in a method as recited in one of Claims 1 through 9.